

$\sin(x)$	$\sinh(x)$	$\arcsin(x)$	$\operatorname{asin}(x)$
$\cos(x)$	$\cosh(x)$	$\arccos(x)$	$\operatorname{acos}(x)$
$\tan(x)$	$\tanh(x)$	$\arctan(x)$	$\operatorname{atan}(x)$
$\csc(x)$	$\operatorname{csch}(x)$	$\operatorname{arccsc}(x)$	$\operatorname{acsc}(x)$
$\sec(x)$	$\operatorname{sech}(x)$	$\operatorname{arcsec}(x)$	$\operatorname{asec}(x)$
$\cot(x)$	$\operatorname{coth}(x)$	$\operatorname{arccot}(x)$	$\operatorname{acot}(x)$

$$\exp(X^Y) \quad \log(X^Y) \quad \ln(X^Y) \quad \det(X^Y) \quad \Pr(X^Y)$$

$$\operatorname{tr} \rho \quad \operatorname{tr}(X^Y) \quad \operatorname{Tr} \rho \quad \operatorname{rank} M \quad \operatorname{erf}(x) \quad \operatorname{Res}[f(z)]$$

$$\mathcal{P} \int f(z) dz \quad \text{P.V.} \int f(z) dz \quad \operatorname{Re}\{z\} \quad \Re \quad \operatorname{Im}\{z\} \quad \Im$$

But

$$\operatorname{Re}\left(\frac{X}{Y}\right) \quad \operatorname{Re}\left[\frac{X}{Y}\right] \quad \operatorname{Im}\left(\frac{X}{Y}\right) \quad \operatorname{Im}\left[\frac{X}{Y}\right]$$

1.4 Quick quad text

[word or phrase][word or phrase]

[,], [c.c.], [if], [then], [else], [otherwise], [unless], [given]
 [using], [assume], [since], [let], [for], [all], [even], [odd],
 [integer], [and], [or], [as], [in]

1.5 Derivatives

$$\begin{array}{cccccc}
d & dx & dx & d^3x & d(\cos \theta) & \\
\frac{d}{dx} & \frac{d}{dx} f & \frac{df}{dx} & \frac{d^n f}{dx^n} & \frac{d}{dx} \left(\frac{X}{Y}\right) & df/dx \\
\frac{\partial}{\partial x} & \frac{\partial}{\partial x} f & \frac{\partial}{\partial x} & \frac{\partial f}{\partial x} & \frac{\partial^n f}{\partial x^n} & \frac{\partial}{\partial x} \left(\frac{X}{Y}\right) & \partial f/\partial x \\
\delta F[g(x)] & \delta(E - TS) & \frac{\delta}{\delta g} & \frac{\delta F}{\delta g} & \frac{\delta}{\delta V}(E - TS) & \delta F/\delta x
\end{array}$$

But

$$d^2\left[\frac{X}{Y}\right]$$

And multiple derivatives, sorta; But only for partial:

$$\frac{\partial^2 f}{\partial x \partial y} \quad \frac{\partial^2 f}{\partial x \partial y} z \quad \frac{\partial^2 f}{\partial x \partial y} z \quad \frac{\partial x}{\partial y}$$

$$\frac{df}{dx} y \quad \frac{\delta F}{\delta f} g$$

1.6 Dirac bra-ket notation

$$\langle \phi | \psi \rangle \quad \text{as opposed to} \quad \langle \phi | \psi \rangle$$

$$\langle \phi | \psi \rangle \langle \xi | \cdot \quad \text{as opposed to} \quad \langle \phi | \psi \rangle \langle \xi |$$

$$\begin{array}{cccccccc} |X^Y\rangle & |X^Y\rangle & \langle X^Y| & \langle X^Y| & & & & \\ \langle \phi | \psi \rangle & \langle \phi | X^Y \rangle & & & \\ \langle a | b \rangle & \langle a | a \rangle & \langle a | X^Y \rangle & \langle a | X^Y \rangle & & & & \\ \langle a | b \rangle & |a\rangle \langle b| & |a\rangle \langle a| & |a\rangle \langle X^Y| & |a\rangle \langle X^Y| & & & \\ |a\rangle \langle b| & \langle A| & \langle \Psi | A | \Psi \rangle & \langle \Psi | A | \Psi \rangle & \langle \Psi | \frac{X}{Y} | \Psi \rangle & \langle X^Y | \frac{X}{Y} | X^Y \rangle & \langle \Psi | \frac{X}{Y} | \Psi \rangle & \\ \langle n | A | m \rangle & \langle n | A | m \rangle & \langle n | \frac{X}{Y} | m \rangle & \langle n | \frac{X}{Y} | X^Y \rangle & \langle n | \frac{X}{Y} | m \rangle & & & \end{array}$$

1.7 Matrix macros

$$\begin{pmatrix} 1 & 0 \\ 0 & 1 \\ a & b \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & a \\ 0 & 1 & b \\ c & d & e \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & a \\ 0 & 1 & b \\ c & d & e \end{pmatrix}$$

But, alignment is illusion

$$\begin{pmatrix} & 1 & 0 & & \frac{x}{y} \\ & 0 & 1 & & b \\ u + v + w + x + y + z & d & & & e \end{pmatrix}$$

$$\begin{array}{ccccccccccc}
a & b & \begin{pmatrix} a & b \\ c & d \end{pmatrix} & \begin{pmatrix} a & b \\ c & d \end{pmatrix} & \begin{bmatrix} a & b \\ c & d \end{bmatrix} & \begin{vmatrix} a & b \\ c & d \end{vmatrix} & \begin{matrix} a & b \\ c & d \end{matrix} & \begin{vmatrix} a & b \\ c & d \end{vmatrix} & \begin{vmatrix} a & b \\ c & d \end{vmatrix} & \begin{vmatrix} a & b \\ c & d \end{vmatrix} \\
\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} & \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} & \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} & \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} & (a_1 \ a_2 \ a_3) & \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \\
\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} & \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} & \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} & \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \\
\begin{pmatrix} 1 & & \\ & 2 & \\ & & 3 \end{pmatrix} & \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix} & \begin{pmatrix} 1 & & \\ & 2 & 3 \\ & 4 & 5 \end{pmatrix} & \begin{pmatrix} & & 1 \\ & 2 & \\ 3 & & \end{pmatrix}
\end{array}$$